

MEMS Approach for Automobiles and Robots

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TOYOTA CRDL., INC.

Outline

1. Sensing Technology for Automobiles
2. Sensors for Automobiles
3. ITS & Probe Car
4. Sensors for Robots
5. Summary

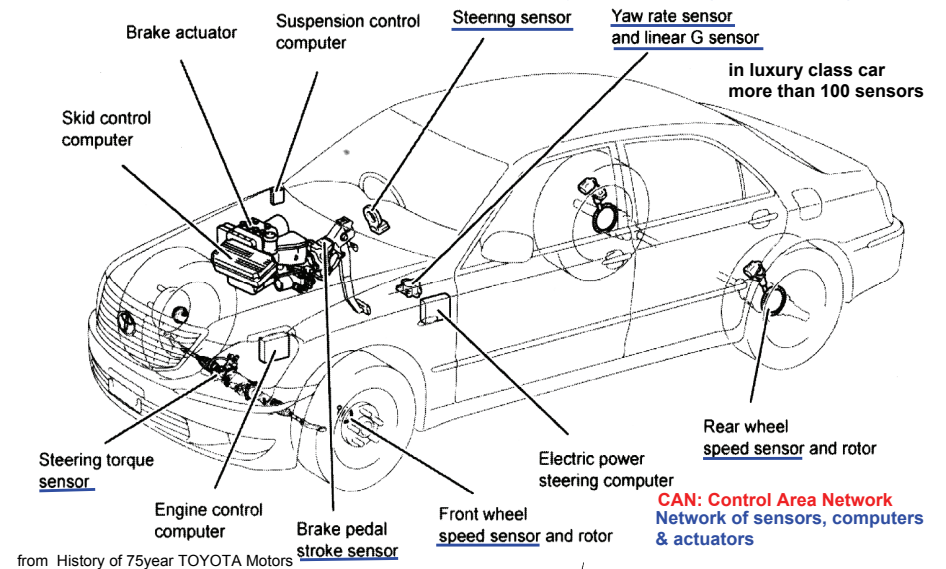
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1. Sensing Technology for Automobiles

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Configuration of VDIM

VDIM: Vehicle Dynamics Integrated Management



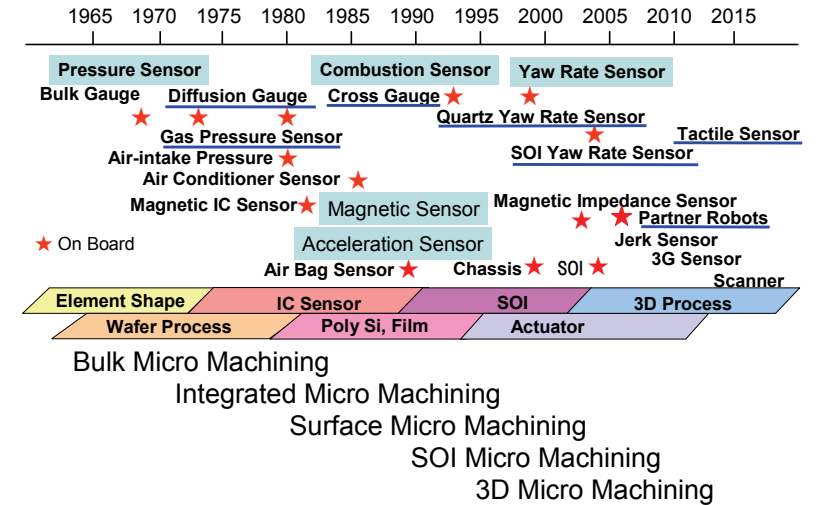
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Kinds of Automotive Sensors

Temperature	Water, Oil, Intake, Exhaust air, Fuel, Cabin
Gas	Oxygen, Lean, NO _x , HC, H ₂
Pressure	Intake air, Air flow, Combustion, Supercharging, Brake, Tire, Compressor
Position	Fuel level, Cam, Vehicle height, Seat
Angle	Crankshaft, rotation, Throttle, Steering, Direction
Speed	Engine, Vehicle, Transmission, Wheel
Angular rate	Yaw rate, Rollover
Acceleration	Airbag, Chassis, Suspension
Force, Load	Brake pedal, Steering torque, Loading
Vibration	Knocking
Light, Electric wave, Sound	Laser, Microwave, Visible light, IR light, Solar irradiation, Headlight, Voice, Ultrasound
Others	Glow plug, Particle, Rain drop, Humidity, Antenna, Fingerprint, Current

Inside Sensor: Pressure, Acceleration, Angular rate (very important to control vehicle)
 Outside Sensor: Sonar, Rader, Vision (expecting advanced safety)

Automotive Sensor & MEMS Technology



2. Sensors for Automobiles

2. Sensors for Automobiles

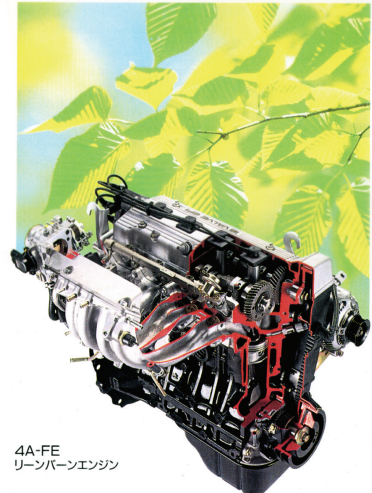
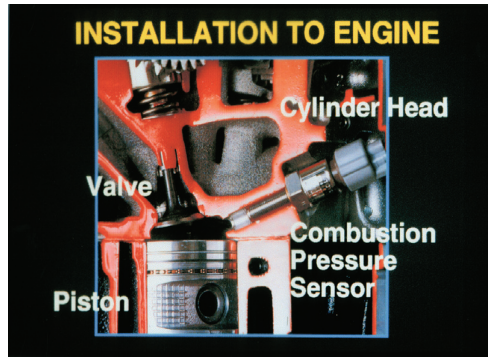
2.1 Piezoresistive effect Sensors

Combustion Pressure Sensor

for Low Exhaust Emission
for Low-fuel Consumption

at High Temperature
700-1200degC
at High Pressure
1-2MPa

—新世代希薄燃焼エンジン—



Lean Burn Engine (TOYOTA)

4A-FE
リーンバーンエンジン

from Y. Nonomura et al., IMechE (1994)

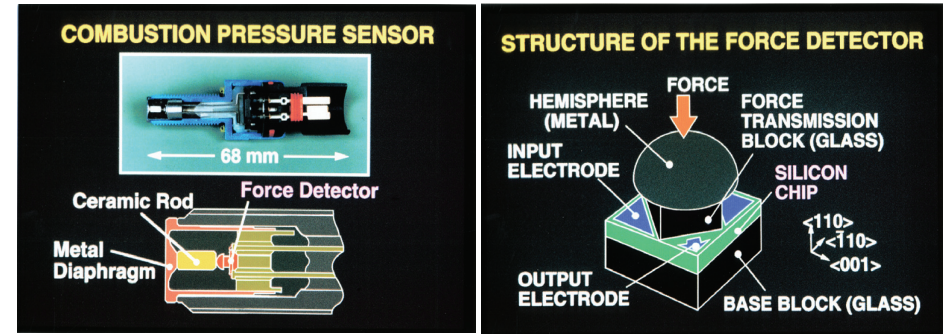
1993

Prize of Japan Society of Mechanical Engineers



Combustion Pressure Sensor

Installed on TOYOTA Lean Burn Engine in 1993



Cross Section View

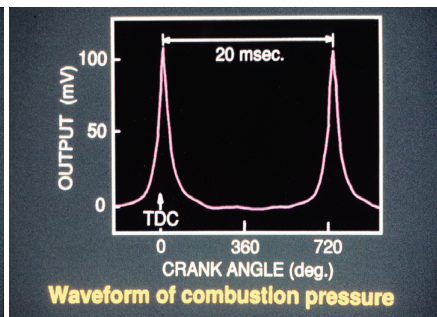
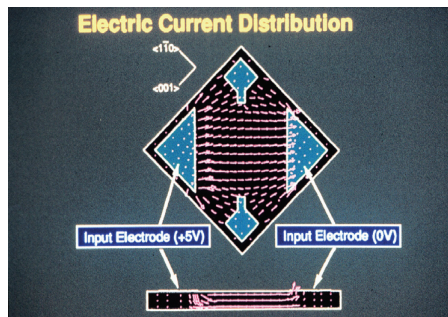
Cross Gauge Type

*Piezoresistive effect of
Semiconductor single crystal Si*

from Y. Nonomura et al., IMechE (1994)



Combustion Pressure Sensor



from Y. Nonomura et al., IMechE (1994)



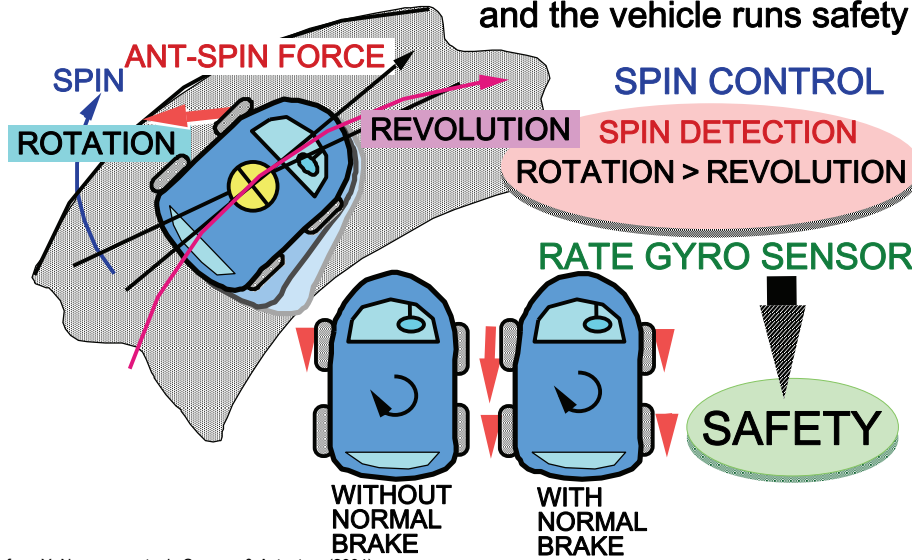
2. Sensors for Automobiles

2.2 Quartz Yaw Rate Sensor



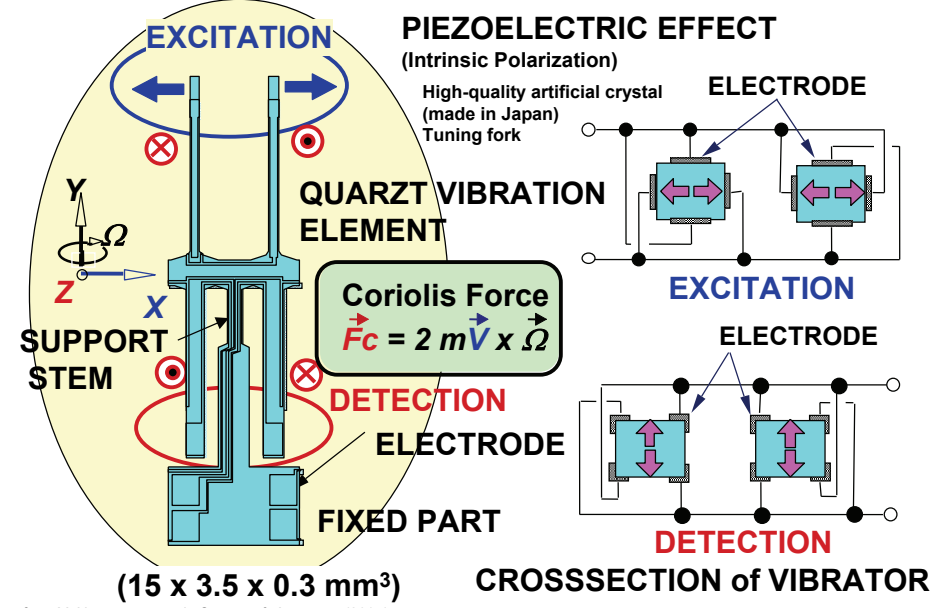
What is VSC

Generate anti-spin force and the vehicle runs safety



from Y. Nonomura et. al., Sensors & Actuators (2004)

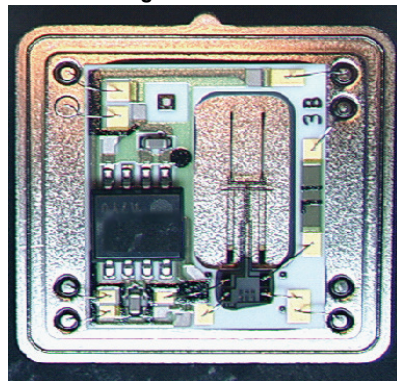
Structure of Quartz Sensor



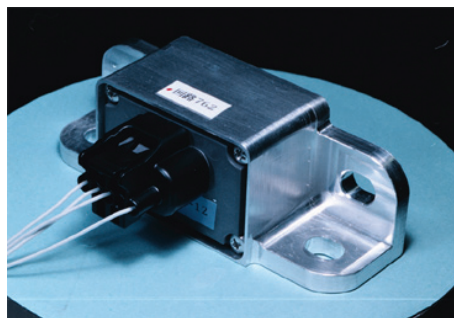
from Y. Nonomura et. al., Sensors & Actuators (2004)

Quartz Yaw Rate Sensor

clear & glitter sensor element



Installed on TOYOTA VSC System in 1998
VSC: Vehicle Stability Control



SENSOR ELEMENT
15 x 3.5 x 0.3 mm³

HOUSING
107 x 48 x 37 mm³

IC PACKAGE SIZE
25 x 25 x 5 mm³

Strong & tough case

from Y. Nonomura et. al., Sensors & Actuators (2004)

2. Sensors for Automobiles

2.3 3-Axis Accelerometer

An SOI 3-Axis Accelerometer with a Zigzag-shaped Z-electrode for Differential Detection

Transducers2011

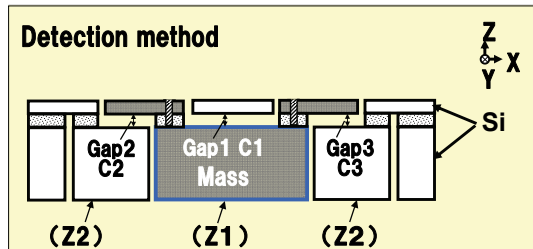
Motivation

- A highly-accurate and reliable 3-axis accelerometer is required for automobiles and robots control.
- Differential detection for Z-axis is essential to improve the accuracy of the accelerometer.

● Zigzag-Shaped Z-electrode (ZSZ)

• Differential detection for Z-axis is achieved with only two Si layers.

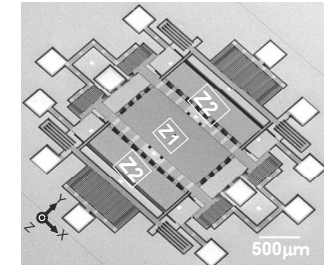
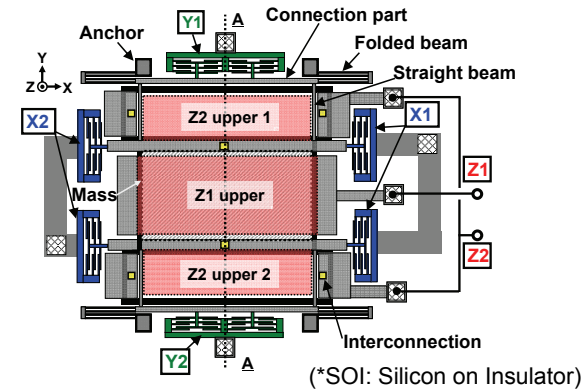
• Gap distances 1-3 are equal by the uniformity of the oxide layer.



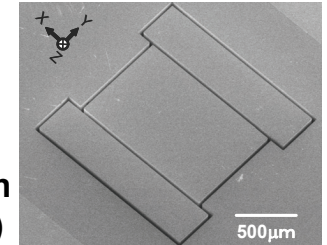
from M. Fujiyoshi, Y. Nonomura, et al. Transducers 2011

Zigzag-Shaped Z-electrode (ZSZ)

SOI 3-Axis Accelerometer with ZSZ



front side



back side

1. SOI* for sensor material
2. All translational motion detection
3. Zigzag-Shaped Z-electrode (ZSZ)

from M. Fujiyoshi, Y. Nonomura, et al. Transducers 2011

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IEEE SENSORS 2014

November 2-5, 2014 • Valencia, Spain

Best Poster Competition

Best Wednesday Poster Award

is presented to

“SOI 3-Axis Accelerometer with a Stress-Reduction Structure”

Motohiro Fujiyoshi¹, Yoshiteru Omura¹, Hirofumi Funabashi¹, Teruhisa Akashi¹, Yoshiyuki Hata¹, Yutaka Nonomura¹, Takahiro

Nakayama², Hitoshi Yamada²

¹Toyota Central R&D labs., Inc., Japan; ²Toyota Motor Corporation, Japan



Ignacio R. Matias
IEEE SENSORS 2014 Technical Program Chair

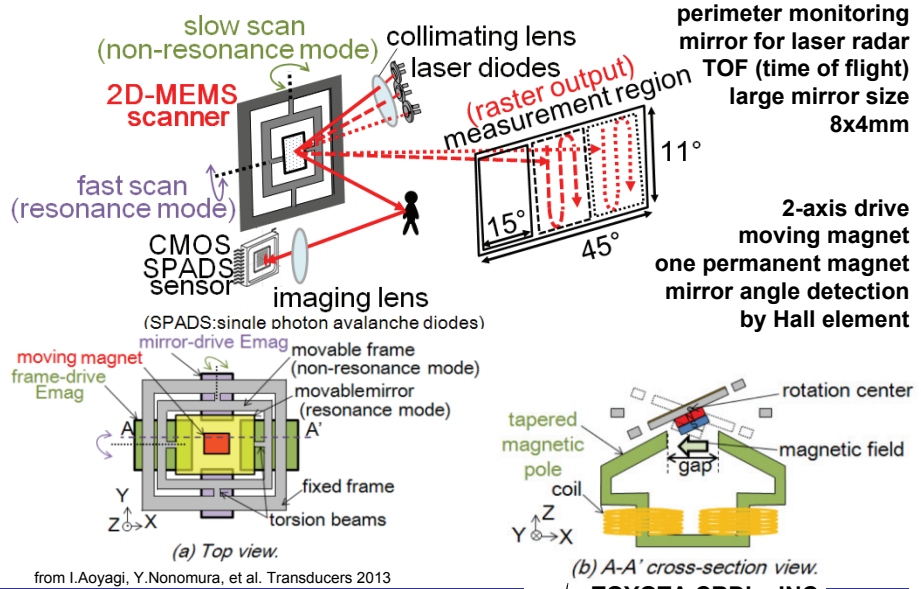


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2. Sensors for Automobiles 2.4 Optical MEMS

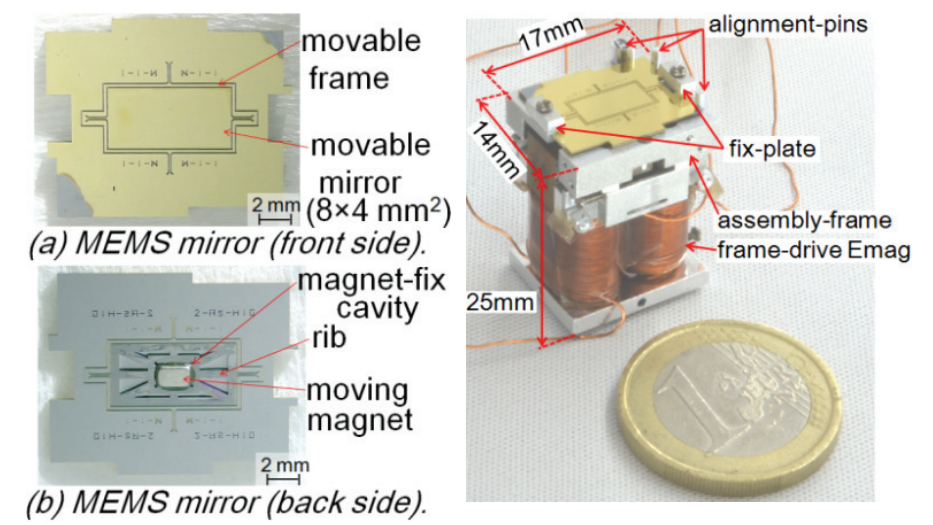
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MEMS Scanner



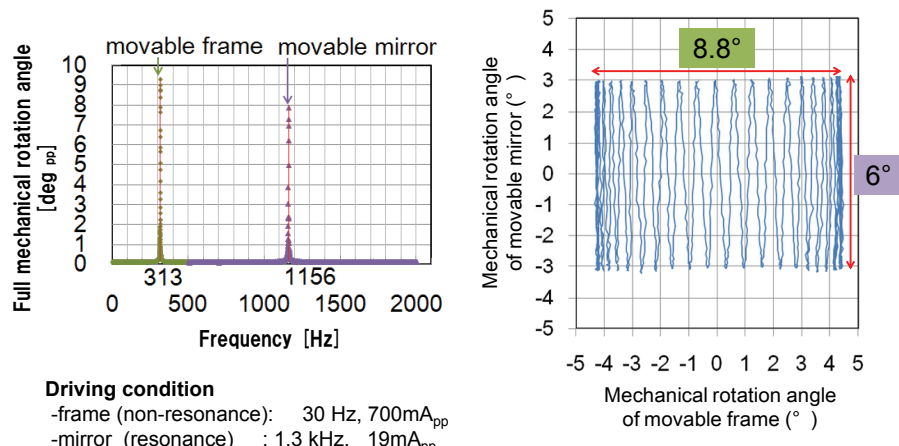
from I.Aoyagi, Y.Nonomura, et al. Transducers 2013

Structure of MEMS Scanner



from I.Aoyagi, Y.Nonomura, et al. Transducers 2013

Characteristics of MEMS Scanner



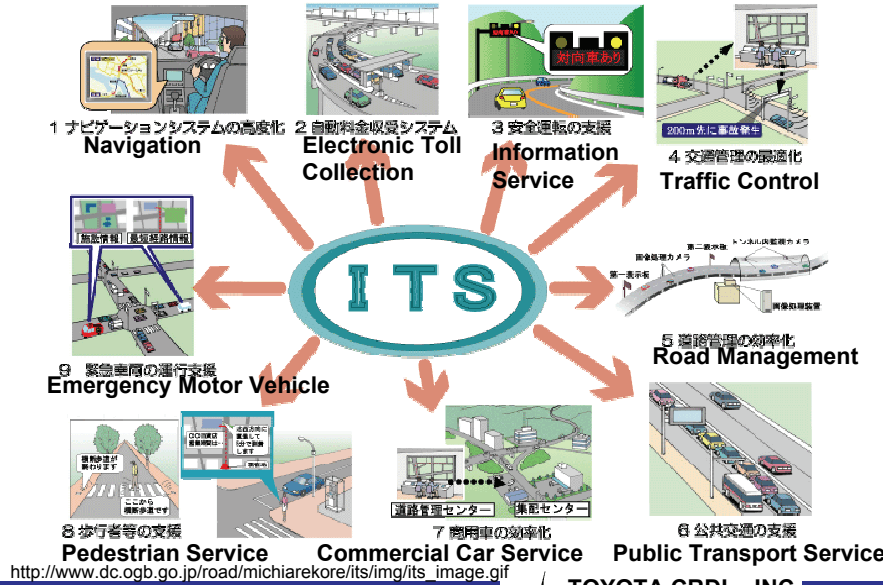
Driving condition
 -frame (non-resonance): 30 Hz, 700mA_{pp}
 -mirror (resonance) : 1.3 kHz, 19mA_{pp}

from I.Aoyagi, Y.Nonomura, et al. Transducers 2013

3. ITS & Probe Car

ITS in Japan

intelligent transportation system



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ITS Sensors



▲光ビーコンヘッド **Optical Beacon**

光ビーコン、路車協調システム、住友電工グループ
<http://www.sei.co.jp/newsletter/2012/10/product.html>



Ultrasonic Sensor



Video Camera

大阪府警察
<https://www.police.pref.osaka.jp/03kotsu/kisei/kansei>
[/kansei03_1.html](http://www.sei.co.jp/newsletter/2012/10/product.html)



Ultrasonic Sensor System

一般社団法人UTMS協会 UTMS:Universal Traffic Management Systems
<http://www.utms.or.jp/japanese/cont/syusyuu/index2.html>

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Probe Car



A road map made by the probe cars

by ITS Japan with TOYOTA, HONDA, NISSAN and Pioneer
 The Great Eastern Japan Earthquake on March 11, 2011
 Very useful for a rescue and transport
 Blue lines are travelable. Red crosses are closures.

Probe Car: GPS (Global Positioning System), map, gyro and speed sensors, and wireless network

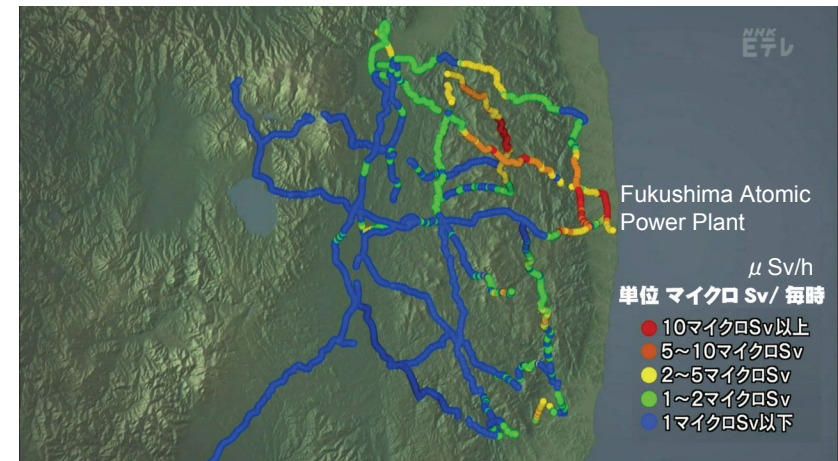
Data Center: data gathering and big data analysis

Car Navigation System or Internet: showing the map immediately

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Probe Car Car & Radiation Sensor

The road to the Fukushima Atomic Power Plant



<http://www.nhk.or.jp/etv21c/file/2011/mapbox/iwaki.html>

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Probe Car

Google Street View

Sensors: GPS, Camera, Laser Rader, Gyro, Speed, Acceleration



<http://www.google.com/maps/about/behind-the-scenes/streetview/privacy/>



http://internet.watch.impress.co.jp/docs/news/20130926_617016.html



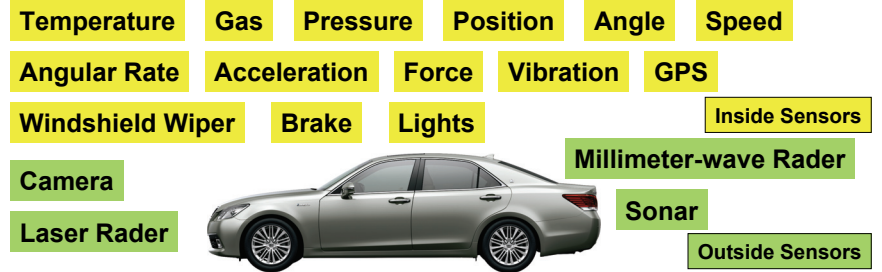
<http://vancouver.keizai.biz/headline/photo/760/>

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Abundance of Automotive Sensors

Automotive Sensors

More than a hundred sensors / car



Annual automobile production is about 100 million .

Total number of sensors in automobiles will be 10 billion a year.



Automobiles keep running around each and every roads on the earth.

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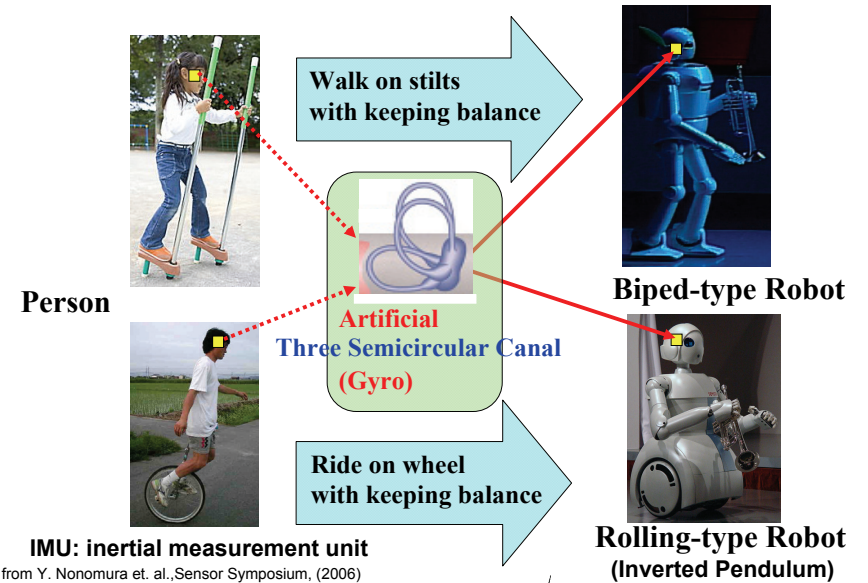
4. Sensors for Robots

4.1 Robot Use of Automotive Sensors

Toyota Group has a dream to create a new world and style of life with robots as partners.

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Role of the Artificial Three Semicircular Canal



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Robots with the Inertial Force Sensing System

Parson Carrier Biped-type Robot



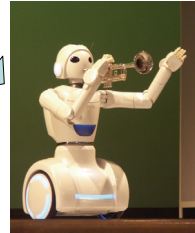
Biped-type Robot
(Plays the Trumpet)



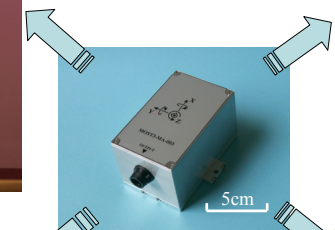
2005
AICHI EXPO



Rolling Type
(2 + 1 wheels)
<i-Swing>
2006
Motor Show



Rolling Type (2 wheels) Robot
(Inverted Pendulum)



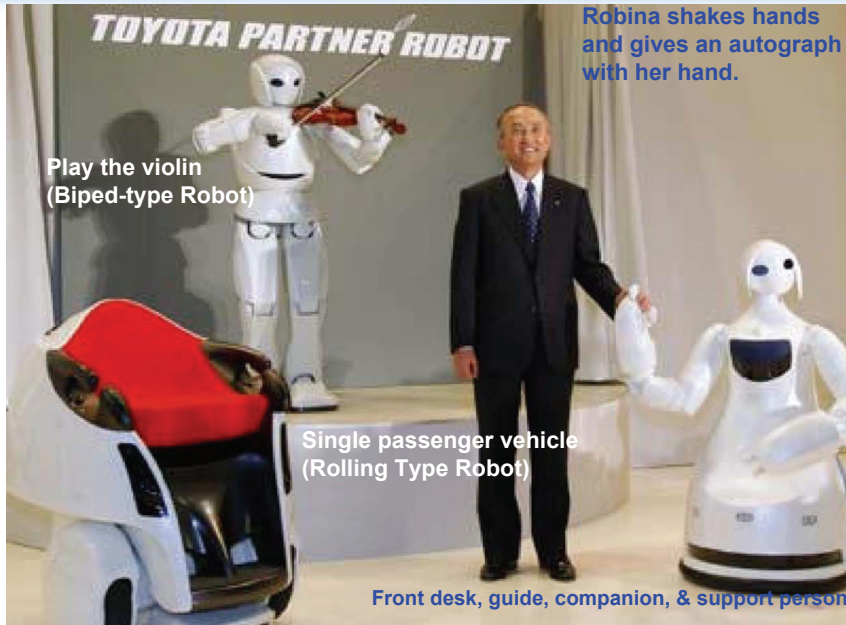
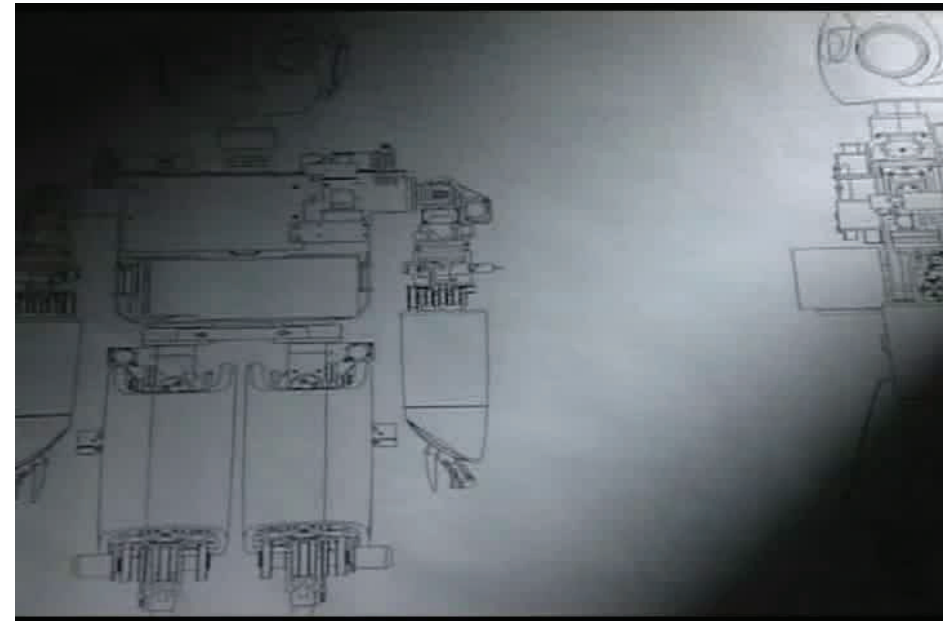
Artificial Three Semicircular Canal

with three gyro sensors,
three acceleration sensors,
and a digital signal Processor

Biped-type Robot with Wire Drive



from Y. Nonomura et. al., Sensor Symposium, (2006)



Play the violin
(Biped-type Robot)

Robina shakes hands
and gives an autograph
with her hand.

Single passenger vehicle
(Rolling Type Robot)

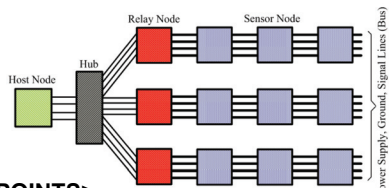
Front desk, guide, companion, & support person

from TOYOTA Motor Corp.

4. Sensors for Robots

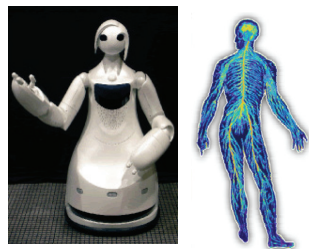
4.2 Tactile Sensor with Nerve Network

Nerve Net Type Tactile Sensor

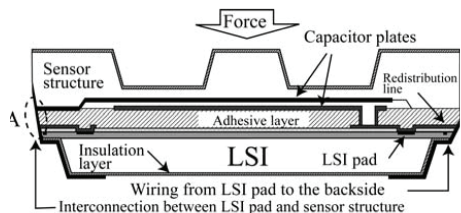


<POINTS>

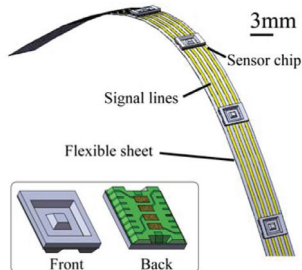
- Serial bus, Event driven against congestion
- Sensor chip on signal processor
- Signal outputs when force changes
- Nerve like relay node (several tens of thousands)



Robina, TOYOTA



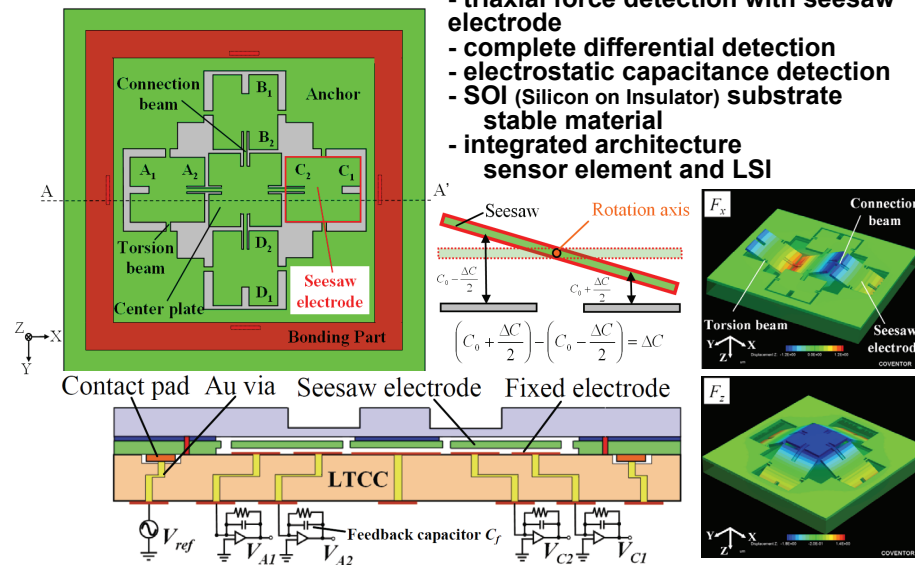
Tactile sensor chip



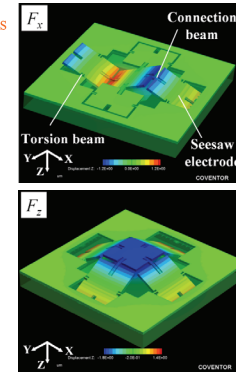
Tactile sensor chip and signal line

from M. Makihata, Y. Nonomura, et al., Transducers 2011

Structure of Tactile Sensor Element



- triaxial force detection with seesaw electrode
- complete differential detection
- electrostatic capacitance detection
- SOI (Silicon on Insulator) substrate
- stable material
- integrated architecture sensor element and LSI

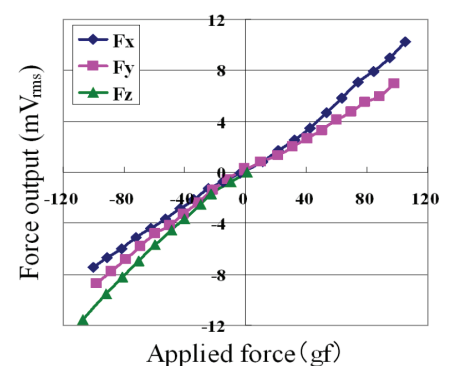


$$\left(C_0 + \frac{\Delta C}{2}\right) - \left(C_0 - \frac{\Delta C}{2}\right) = \Delta C$$

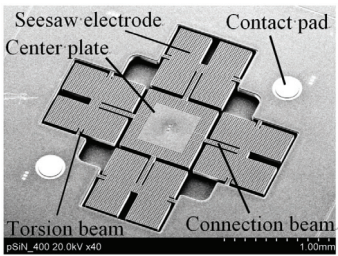
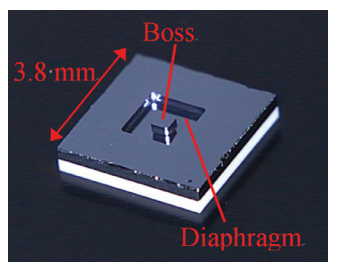
from Y. Hata, Y. Nonomura, et al., MEMS 2014

- LTCC (Low Temperature Co-fired Ceramic)

Characteristic of Sensor Element



$$\begin{pmatrix} F_x \\ F_y \\ F_z \\ 0 \end{pmatrix} = \frac{1}{4} \cdot \begin{pmatrix} 2 & 0 & -2 & 0 \\ 0 & 2 & 0 & -2 \\ 1 & 1 & 1 & 1 \\ 0 & 0 & 0 & 0 \end{pmatrix} \cdot \begin{pmatrix} \Delta V_A \\ \Delta V_B \\ \Delta V_C \\ \Delta V_D \end{pmatrix}$$



from Y. Hata, Y. Nonomura, et al., MEMS 2014

5. Summary

- **Sensors** for automobiles have been advanced with the **MEMS** technology.
- **New sensors** are created with **new MEMS technology**. The technology will continue to grow.
- The sensors for the automobiles are connected to **the intranet (CAN)** for high performance and to **the internet** with **wireless** communication systems (ITS & probe car).
- The automotive sensors are useful for robots. **The partner robots** need **new technologies** and **new sensors**.